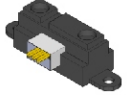


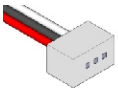
# Sensing Distance (SHARP GP2Y0A21YK)



## The Pieces

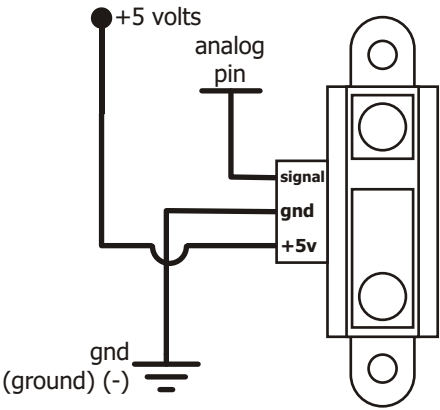


**IR Distance Sensor**  
(Sharp GP2Y0A21Y)  
**x1**



**Cable**  
(JST 3 pole)  
**x1**

## The Schematic



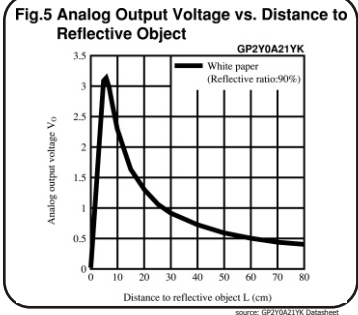
## The Theory & Code

### Infra Red Distance Sensor

An analog IR distance sensor is a really neat component. Simply connect +5v and ground and a voltage proportional to the distance between the sensor and an object in front of it will be returned (ranging from 0.4 volts at 80 cm to 3 volts at 10 cm). It really couldn't be simpler to use.

### Converting to Distance

The voltage returned is not linear (see graph), however it can be converted to a distance using some simple maths. There will be some variation between models but here are a couple of equations that worked for us (results +-~5%)



### Equations

**From 10 bit A/D Reading to centimeters (5v supply)**  
 $distance = 12343.85 * (10bit\ reading)^{-1.15}$

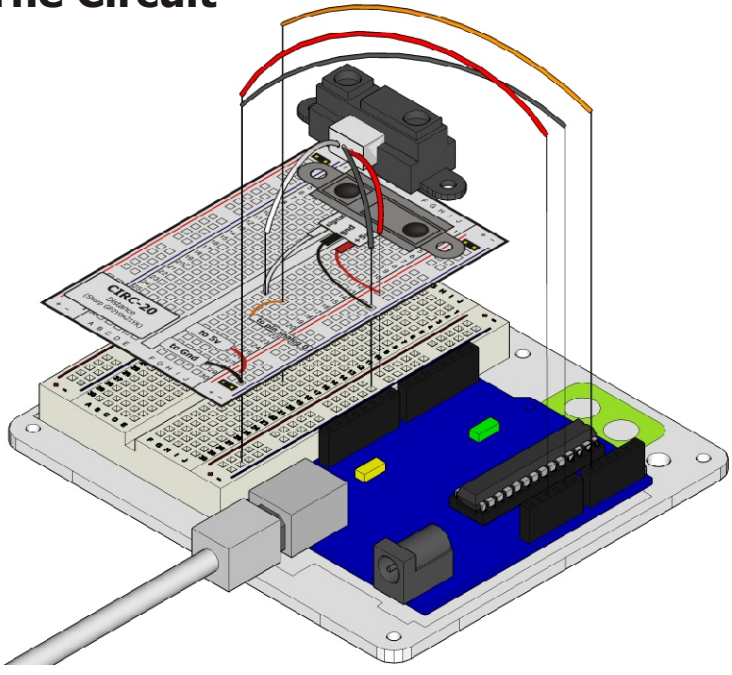
**From Voltage Reading to Centimeters**  
 $distance = 27.86 * (voltage\ reading)^{-1.15}$

**Arduino Code (5v)**  
 $float\ distance = 12343.85 * pow(analogRead(sensorPin), -1.15)$

### Technical Details

∴ Full Datasheet: <http://tinyurl.com/yh7chku> ∴

## The Circuit



## The Layout Sheet

